

Stationary Points for Multifunctions on Two Complete Metric Spaces

VALERIU POPA

ABSTRACT. In this paper we prove a general fixed point theorem for multifunctions on two complete metric spaces which generalizes the main results from [2] and [5].

1. INTRODUCTION

Let (X, d) be a complete metric space and let $B(X)$ be the set of all nonempty subsets of X . As in [1] we define the function $\delta(A, B)$ with A and B in $B(X)$ by $\delta(A, B) = \sup\{d(a, b) : a \in A, b \in B\}$.

If A consists of a single point we write $\delta(A, B) = \delta(a, B)$. If B also consists of single point b then $\delta(a, b) = d(a, b)$. It follows immediately that: $\delta(A, B) = \delta(B, A) \geq 0$ and $\delta(A, B) \leq \delta(A, C) + \delta(C, B)$ for A, B, C in $B(X)$. If $\delta(A, B) = 0$ then $A = B = \{a\}$.

Now if $\{A_n : n = 1, 2, \dots\}$ is a sequence in $B(X)$, we say that it converges to the set A in $B(X)$ if:

- (i) each point $a \in A$ is limit of some convergent sequence $\{a_n \in A_n : n = 1, 2, \dots\}$;
- (ii) for arbitrary $\epsilon > 0$, there exists an integer N such that $A_n \subset A_\epsilon$ for $n > N$, where A_ϵ is the union of all open spheres with centers in A of radius ϵ .

The set A is said to be limit of the sequence $\{A_n\}$.

The following Lemma was proved in [1].

Lemma 1.1. *If $\{A_n\}$ and $\{B_n\}$ are sequences of bounded subsets of a complete metric space (X, d) which converges to the bounded subsets A and B , respectively, then the sequence $\{\delta(A_n, B_n)\}$ converges to $\delta(A, B)$.*

Let T be a multifunction of X into $B(X)$. z is a stationary point of T if $Tz = \{z\}$.

In 1981, Fisher [2] initiated the study of fixed points on two metric spaces. In 1991, the present author [5] proved other theorems on two metric spaces.

2000 *Mathematics Subject Classification.* Primary 54H25.

Key words and phrases. fixed point, multifunction, implicit relation, complete metric space.

The following fixed points theorems are proved in [2], resp. [5].

Theorem 1.1 ([2]). . Let (X, d) and (Y, ρ) be complete metric spaces. If T is a mapping of X into Y and S is a mapping of Y into X satisfying the inequalities

$$\begin{aligned}\rho(Tx, TSy) &\leq c \max\{d(x, Sy), \rho(y, Tx), \rho(y, TSy)\}, \\ d(Sy, STx) &\leq c \max\{\rho(y, Tx), d(x, Sy), d(x, STx)\}\end{aligned}$$

for all x in X and y in Y , where $0 \leq c < 1$, then ST has a unique fixed point z in X and TS has a unique fixed point w in Y . Further, $Tz = w$ and $Sw = z$.

Theorem 1.2 ([5]). Let (X, d) and (Y, e) be complete metric spaces. If T is a mapping of X into Y and S is a mapping of Y into X satisfying the inequalities

$$\begin{aligned}e^2(Tx, TSy) &\leq c_1 \max\{d(x, Sy)e(y, Tx), d(x, Sy)e(y, TSy), e(y, Tx)e(y, TSy)\}, \\ d^2(Sy, STx) &\leq c_2 \max\{e(y, Tx)d(x, Sy), e(y, Tx)d(x, STx), d(x, Sy)d(x, STx)\}\end{aligned}$$

for all x in X and y in Y , where $0 \leq c_1, c_2 < 1$, then ST has a unique fixed point z in X and TS has a unique fixed point w in Y . Furthermore, $Tz = w$ and $Sw = z$.

Recently, some fixed points theorems for multifunctions on two complete metric spaces have been proved in [3], [4], [6].

In this paper we prove two generalizations of Theorems 1 and 2 for single valued and set valued mappings satisfying two implicit relations.

2. IMPLICIT RELATIONS

Let \mathcal{F}_4 be the set of all continuous functions $F : R_+^4 \rightarrow R$ such that:

(F_1): F is nonincreasing in variables t_2, t_3 ;

(F_2): there exists $h \in [0, 1)$ such that for every $u \geq 0, v \geq 0$ with:

a) $F(u, 0, u, v) \leq 0$ or b) $F(u, u, 0, v) \leq 0$

we have $u \leq hv$.

Example 2.1. $F(t_1, \dots, t_4) = t_1 - k \max\{t_2, t_3, t_4\}$ where $k \in [0, 1)$.

(F_1): Obviously.

(F_2): Let $u > 0$ and $F(u, 0, u, v) = u - k \max\{u, v\} \leq 0$.

If $u \geq v$ then $u(1 - k) \leq 0$, a contradiction.

Thus $u < v$ and $u \leq hv$. Similarly, $F(u, u, 0, v) \leq 0$ implies $u \leq hv$.

If $u = 0$, then $u \leq hv$.

Example 2.2. $F(t_1, \dots, t_4) = t_1^2 - c \max\{t_2t_4, t_2t_3, t_3t_4\}$ where $c \in [0, 1)$.

(F_1): Obviously.

(F_2): Let $u > 0$ and $F(u, 0, u, v) = u^2 - cuv \leq 0$, which implies $u \leq hv$, where $h = c \in [0, 1)$.

Similarly, $F(u, u, 0, v) \leq 0$ implies $u \leq hv$.

If $u = 0$, then $u \leq hv$.

Example 2.3. $F(t_1, \dots, t_4) = t_1^3 - (at_1^2t_2 + bt_3^3 + ct_4^3)$ where $a, b, c > 0$ and $a + b + c < 1$.

(F_1): Obviously.

(F_2): $F(u, 0, u, v) = u^3 - [bu^3 + cv^3] \leq 0$ implies $u \leq h_1v$, where $h_1 = (\frac{c}{1-b})^{\frac{1}{3}} < 1$.

Similarly, $F(u, u, 0, v) \leq 0$ implies $u \leq h_2v$, where $h_2 = (\frac{c}{1-a})^{\frac{1}{3}} < 1$. Let $h = \max\{h_1, h_2\}$, then $u \leq hv$.

Example 2.4. $F(t_1, \dots, t_4) = t_1 - c\frac{t_2+t_3+t_4}{1+t_4}$ where $0 \leq c < \frac{1}{2}$

(F_1): Obviously.

(F_2): $F(u, 0, u, v) = u - c\frac{u+v}{1+v}$ implies $u - c(u+v) \leq 0$ and $u \leq hv$, where $h = \frac{c}{1-c} < 1$. Similarly, $F(u, u, 0, v) \leq 0$ implies $u \leq hv$.

3. MAIN RESULTS

Theorem 3.1. *Let (X, d_1) and (Y, d_2) be two complete metric spaces and let F be a mapping of X into $B(Y)$ and let G be a mapping of Y into $B(X)$ satisfying the inequalities:*

$$(1) \quad \Phi_1(\delta_1(GFx, Gy), d_1(x, Gy), \delta_1(x, GFx), \delta_2(y, Fx)) \leq 0$$

$$(2) \quad \Phi_2(\delta_2(FGy, Fx), d_2(y, Fx), \delta_2(y, FGy), \delta_1(x, Gy)) \leq 0$$

for all x in X and y in Y , where $\Phi_1, \Phi_2 \in \mathcal{F}_4$, then GF has a stationary point z in X and FG has a stationary point w in Y . Furthermore, $Fz = \{w\}$ and $Gw = \{z\}$.

Proof. Let x_1 be an arbitrary point in X . Define sequences $\{x_n\}$ and $\{y_n\}$ in X and Y , respectively, as follows: choose a point y_1 in Fx_1 and a point x_2 in Gy_1 . In general, having chosen x_n in X and y_n in Y , we choose x_{n+1} in Gy_n and then y_{n+1} in Fx_{n+1} for $n = 1, 2, \dots$

Then, by (1), we have successively

$$\Phi_1(\delta_1(GFx_{n+1}, Gy_n), d_1(x_{n+1}, Gy_n), \delta_1(x_{n+1}, GFx_{n+1}), \delta_2(y_n, Fx_{n+1})) \leq 0$$

$$\Phi_1(\delta_1(GFx_{n+1}, Gy_n), 0, \delta_1(Gy_n, GFx_{n+1}), \delta_2(y_n, Fx_{n+1})) \leq 0$$

which implies

$$(3) \quad \delta_1(GFx_{n+1}, Gy_n) \leq h\delta_2(y_n, Fx_{n+1}).$$

By (2) we have successively

$$\Phi_2(\delta_2(FGy_n, Fx_n), d_2(y_n, Fx_n), \delta_2(y_n, FGy_n), \delta_1(x_n, Gy_n)) \leq 0$$

$$\Phi_2(\delta_2(FGy_n, Fx_n), 0, \delta_2(Fx_n, FGy_n), \delta_1(x_n, Gy_n)) \leq 0$$

which implies

$$(4) \quad \delta_2(FGy_n, Fx_n) \leq h_2\delta_1(x_n, Gy_n).$$

Thus, it follows from (3) and (4) that

$$\begin{aligned} d_1(x_{n+1}, x_{n+2}) &\leq \delta_1(Gy_n, GFx_{n+1}) \leq h_1\delta_2(y_n, Fx_{n+1}) \leq h_1\delta_2(Fx_n, GFy_n) \leq \\ &\leq h_1h_2\delta_1(x_n, Gy_n) \leq \dots (h_1h_2)^n\delta_1(x_1, GFx_1). \end{aligned}$$

Similarly, we can prove that

$$d_2(y_{n+1}, y_n) \leq (h_1h_2)^n\delta_2(y_1, FGy_1).$$

Now, it follows that for $n = 1, 2, \dots$ and $r \in N^*$

$$\begin{aligned} d_1(x_{n+1}, x_{n+r+1}) &\leq \delta_1(Gy_n, GFx_{n+r}) \leq \\ &\leq \delta_1(Gy_n, Gy_{n+1}) + \delta_1(Gy_{n+1}, y_{n+2}) + \dots + \\ &\quad + \delta_1(Gy_{n+r-1}, GFx_{n+r}) \leq \\ &\leq \delta_1(Gy_n, GFx_{n+1}) + \delta_1(Gy_{n+1}, GFx_{n+2}) + \dots + \\ &\quad + \delta_1(Gy_{n+r-1}, GFx_{n+r}) \leq \\ &\leq \{(h_1h_2)^n + (h_1h_2)^{n+1} + \dots + (h_1h_2)^{n+r-1}\}\delta_1(x_1, GFx_1) < \epsilon \end{aligned}$$

for n greater than some N since $h_1h_2 < 1$.

Therefore, the sequence $\{x_n\}$ is a Cauchy sequence in the complete metric space X and so it has a limit z in X .

Similarly, the sequence $\{y_n\}$ is a Cauchy sequence in the complete metric space Y and so it has a limit w in Y .

Further

$$\begin{aligned} \delta_1(z, GFx_n) &\leq d_1(z, x_{m+1}) + \delta_1(x_{m+1}, GFx_n) \leq \\ &\leq d_1(z, x_{m+1}) + \delta_1(Gy_m, GFx_n) \\ &\leq d_1(z, x_{m+1}) + \epsilon \text{ for } m, n > N. \end{aligned}$$

Letting m tend to infinity it follows that

$$\delta_1(z, GFx_n) < \epsilon$$

for $n > N$ and

$$(5) \quad \lim GFx_n = z = \lim Gy_n.$$

Similarly,

$$(6) \quad \lim FGy_n = w = \lim Fx_n.$$

Using inequality (2) and (F_1) we have

$$\Phi_2(\delta_2(FGy_n, Fz), \delta_2(y_n, Fz), \delta_2(y_n, FGy_n), \delta_1(z, Gy_n)) \leq 0.$$

Letting n tend to infinity we obtain successively

$$\Phi_2(\delta_2(w, Fz), \delta_2(w, Fz), \delta_2(w, w), \delta_1(z, z)) \leq 0$$

$$\Phi_2(\delta_2(w, Fz), \delta_2(w, Fz), 0, 0) \leq 0$$

which implies $\delta_2(w, Fz) = 0$. Thus

$$(7) \quad Fz = \{w\}.$$

Similarly, we can prove that

$$(8) \quad Gw = \{z\}.$$

From (7) and (8), it follows that

$$GFz = Gw = \{z\} \quad \text{and} \quad FGw = Fz = \{w\}.$$

Thus z is a stationary point of GF and w is a stationary point of FG . This completes the proof of Theorem 3. \square

Theorem 3.2. *Let (X, d_1) and (Y, d_2) be two complete metric spaces and let f be a single valued mapping of X into Y and g a single valued mapping of Y into X satisfying the inequalities*

$$(1') \quad \Phi_1(d_1(gfx, gy), d_1(x, gy), d_1(x, gfx), d_2(y, fx)) \leq 0$$

$$(2') \quad \Phi_2(d_2(fgy, fx), d_2(y, fx), d_2(y, fgy), d_1(x, gy)) \leq 0$$

for all x in X and y in Y , where $\Phi_1, \Phi_2 \in \mathcal{F}_4$.

Then gf has an unique fixed point z in X and fg has an unique fixed point w in Y . Further, $fz = w$ and $gw = z$.

Proof. The existence of z and w follows from Theorem 3. Now suppose that gf has a second fixed point z' .

Then by (1') we have successively

$$\Phi_1(d_1(gfz, gfz'), d_1(z, gfz'), d_1(z, gfz), d_2(fz', fz)) \leq 0$$

$$\Phi_1(d_1(z, z'), d(z, z'), 0, d(fz, fz')) \leq 0$$

which implies

$$(9) \quad d(z, z') \leq h_1 d(fz, fz').$$

Similarly, by (2') we have successively

$$\Phi_2(d_2(fgfz, fz'), d_2(fz, fz'), d_2(fz, fgfz), d_1(z', gfz)) \leq 0$$

$$\Phi_2(d_2(fz, fz'), d(fz, fz'), 0, d(z, z')) \leq 0$$

which implies

$$(10) \quad d_2(fz, fz') \leq h_2 d(z, z').$$

By (9) and (10) we have

$$d_1(z, z_1) \leq h_1 d_2(fz, fz') \leq (h_1 h_2) d_1(z, z').$$

Since $h_1 h_2 < 1$ it follows that $z = z'$.

Similarly fg has a unique fixed point. \square

Corollary 3.1. *Theorem 1.1.*

Proof. The proof follows from Theorem 3.2 and Example 1. \square

Corollary 3.2. *Theorem 1.2.*

Proof. The proof follows from Theorem 3.2 and Example 2. \square

REFERENCES

- [1] Fisher, B., *Common fixed points of mappings and set valued mappings*, Rostok Math.Kolloq. **8**(1981), 68–77.
- [2] Fisher, B., *Fixed points on two metric spaces*, Glasnik Mat. **16(36)**,(1981), 333–337.
- [3] Fisher, B. and Türköglu,D., *Related fixed point for set valued mappings on two metric spaces*, Internat. J.Math.Math.Sci. **23**(2000), 205–210.
- [4] Liu Z., Liu Q., *Stationary points for set-valued mappings on two metric spaces*, Rostok Math. Kolloq. **55**(2001), 23–29.
- [5] Popa V., *Fixed points on two complete metric spaces*, Zb.Rad.Prirod.Mat.Fiz. Ser.Mat.Univ. Novom Sadu, **21**(1991),83–93.
- [6] Popa V., *Two general fixed point theorem for mappings on two metric spaces*, Anal.Univ.Galați, fasc.II. Mat.Fiz.Mec.Teor.Suppl. vol.18(**23**)(2001),19–24.

DEPARTMENT OF MATHEMATICS
UNIVERSITY OF BACĂU
5500 BACĂU, ROMANIA
E-mail address: vpopa@ub.ro